## Chance constrained optimization of a three-stage launcher

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We are interested in optimizing the fuel load of a three-stage launcher which mission is to deliver a payload to a given altitude. Since some of the system's parameters are subject to uncertainties, the aim is to guarantee the success of the mission with a 90% probability, taking into account those random variations.

A general formulation of our stochastic optimization problem would be

$$\begin{cases} \text{Calculate} \\ \min_{x \in X} J(x) \\ \text{Subject to} \\ \mathbb{P}[G(x, \omega) \leq 0] \geq p \end{cases}$$

where  $x \in X \subset \mathbb{R}^n$  is the array of optimization variables,  $\omega \in \Omega \subset \mathbb{R}^n$  is an array of random variable with known distribution and  $0 \leq p \leq 1$  represents the probability of success. Our approach consists in translating this stochastic optimization problem into a deterministic one by approximating the distribution of the constraint function G (which is a random variable, since it depends on  $\omega$ ) via Kernel Density Estimation. Let s be a random variable with an unknown probability density function f that we want to estimate and let  $\{s_1, s_2, \ldots, s_n\}$  be a sample of size m from the variable s. A Kernel Density Estimator for f is the function

$$\hat{f}(x) := \frac{1}{mh} \sum_{i=1}^{m} K\left(\frac{x - s_i}{h}\right)$$

where the function K is called *kernel* and the smoothing parameter h is called *bandwidth*. The approximation error between f and  $\hat{f}$  depends on the choice of both K and h. Since the bandwidth plays a much more important role than the kernel (see [1]), in most applications the study is focused on the choice of h. K is usually the Gaussian kernel.

## References

[1] S. J. SHEATHER, Density Estimation, Statistical Science 19(4), 588-597, 2004.