# Learning in Mean Field Games: The Fictitious Play

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#### **1** Introduction to Mean Field Games (MFG)

- Model
- Mean Field Game Equilibrium

#### Fictitious Play in Mean Field Game

- Fictitious Play
- Potential Mean Field Game
- Second Order MFG
- First Order MFG
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  - Jeux à champ moyen. II. Horizon fini et contrôle optimal. C. R. Math. Acad. Sci. Paris 343 (2006), no. 10, 679-684.
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- M. Huang, R.P. Malhamè and P.E. Caines:
  - Large population stochastic dynamic games: closed-loop McKean-Vlasov systems and the Nash certainty equivalence principle. Communication in information and systems (2006). Vol. 6, No. 3, pp. 221-252.

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- Consider a typical player: at every time  $t \in [0, T]$  he has a state  $x_t \in X$  with controlling it by  $\alpha_t$ :

$$\mathrm{d}x_t = \alpha_t \mathrm{d}t + \sqrt{2\sigma} \mathrm{d}B_t$$

where  $B_t$  is a Brownian motion adapted to some filtration  $(\mathcal{F}_t)_{t \in [0,T]}$ . In stochastic case  $(\sigma \neq 0)$  we suppose  $\alpha_t$  is adapted to  $\mathcal{F}_t$ .

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- The distribution of states of players at time t is denoted by  $m_t \in \mathcal{P}(X)$ .
- The case  $\sigma = 0(1)$  is called *First(Second) Order* MFG.

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 $\mathcal{J}(\alpha, (m_t)_{t \in [0,T]}) = \mathbb{E}\left(\int_0^T \left(L(x_t, \alpha_t) + f(x_t, m_t)\right) dt + g(x_T, m_T)\right)$ 

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• Best reply to the rest of population:

 $\operatorname{argmin}_{\alpha \in (\mathcal{F}_t)_{t \in [0,T]}} \mathcal{J}(\alpha, (m_t)_{t \in [0,T]})$ 

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- Value Function  $u: [0,T] \times \mathbb{T}^d \to \mathbb{R}$ :

$$u(s, x) =$$

$$\inf_{x_s=x, dx_t=\alpha_t dt+\sigma dB_t} \mathbb{E}\left(\int_s^T \left(L(x_t, \alpha_t) + f(x_t, m_t)\right) dt + g(x_T, m_T)\right)$$

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• HJB Equation:

 $-\partial_t u - \sigma \Delta u + H(x, \nabla u) = f(x, m_t)$   $u(x, T) = g(x, m_T)$  where  $H(x, p) = -\inf_q \langle p, q \rangle + L(x, q).$ 

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• HJB Equation:

$$\begin{split} &-\partial_t u - \sigma \Delta u + H(x, \nabla u) = f(x, m_t) \\ &u(x,T) = g(x,m_T) \\ &\text{where } H(x,p) = -\inf_q \langle p,q \rangle + L(x,q). \\ \bullet \ \alpha(t,x) = -D_p H(x, \nabla u(t,x)) \text{ the best reply in feedback form.} \end{split}$$

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• HJB Equation:

$$-\partial_t u - \sigma \Delta u + H(x, \nabla u) = f(x, m_t)$$
$$u(x, T) = g(x, m_T)$$
$$(x, n) = -\inf_{x \to 0} f(x, n_t) + L(x, n_t)$$

where  $H(x, p) = -\inf_q \langle p, q \rangle + L(x, q).$ 

- $\alpha(t,x) = -D_p H(x, \nabla u(t,x))$  the best reply in feedback form.
- The key point is that the agent assumes  $m_t \in \mathcal{P}(X), t \in [0, T]$  as given.

If every one choose their best replies:

$$\alpha(t,x) = -D_p H(x, \nabla u(t,x))$$

then the distribution evolves by Fokker-Planck (or continuity) Equation:

$$\partial_t m - \sigma \Delta m + \operatorname{div}(\alpha(t, x)m) = 0$$
  
 $m(0) = m_0.$ 

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#### $\text{Belief} \Rightarrow \quad \text{Best Reply} \Rightarrow \quad \text{Reality Occurs}$

# Belief $\Rightarrow$ Best Reply $\Rightarrow$ Reality Occurs $(m_t^B)_{t \in [0,T]} \Rightarrow^{HJB} (\alpha_t)_{t \in [0,T]} \Rightarrow^{FP} (m_t^R)_{t \in [0,T]}$

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Mean Field Game Equilibrium is represented by the solution of the following coupled equations:

$$\begin{cases} (i) & -\partial_t u - \sigma \Delta u + H(x, \nabla u) = f(x, m(t)) \text{ in } (0, T) \times \mathbb{R}^d \\ (ii) & \partial_t m - \sigma \Delta m - \operatorname{div}(mD_p H(x, \nabla u)) = 0 \text{ in } (0, T) \times \mathbb{R}^d \\ (iii) & m(0) = m_0, \ u(x, T) = g(x, m(T)) \text{ in } \mathbb{R}^d \end{cases}$$

#### Theorem (P.L. Lions, J.M. Lasry)

Suppose the following (\*) conditions hold:

- $m_0$  has a smooth density.
- $H \in \mathcal{C}^2(\mathbb{T}^d \times \mathbb{R}^d), \exists C > 0 : C^{-1}I_d \le D_{pp}H(x,p) \le CI_d,$
- $\langle D_x H(x,p), p \rangle \ge -C(1+\|p\|^2),$
- $f: m \to f(\cdot, m)$  is Lipchitz from  $\mathcal{P}(\mathbb{T}^d)$  to  $\mathcal{C}^2(\mathbb{T}^d)$ ,
- $g: m \to g(\cdot, m)$  is Lipschitz from  $\mathcal{P}(\mathbb{T}^d)$  to  $\mathcal{C}^3(\mathbb{T}^d)$ ,
- $\sup_{m \in \mathcal{P}(\mathbb{T}^d)} \|f(\cdot, m)\|_{\mathcal{C}^2} + \|g(\cdot, m)\|_{\mathcal{C}^3} < +\infty.$

Then the there exist (u, m) which satisfy MFG Equilibrium equation in strong(weak) sense in case  $\sigma \neq 0 (= 0)$ . In addition, if f, g are monotone, then the equilibrium is unique.

We call  $h : \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \to \mathbb{R}$  monotone if for every distinct  $m, m' \in \mathcal{P}(\mathbb{T}^d)$ :

$$\int_{\mathbb{T}^d} \left( h(x,m) - h(x,m') \right) \mathrm{d}(m-m')(x) > 0$$

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- The game is played recursively:  $x(0) \in A$  is arbitrary,

$$\forall j \in \mathbb{N}^*, \forall i \in \{1, 2, \dots, N\} : \quad x_i(j+1) \in \operatorname{argmin}_{x_i \in A_i} C_i(x_i, \bar{x}_{-i}(j)),$$
  
where  $\bar{x}_k(j) = \frac{\sum_{w=1}^j x_k(w)}{j}.$ 

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- Question: the accumulation points of the sequence  $\{\bar{x}(j)\}_{j\in\mathbb{N}}\subset\Delta(A)$  are Nash equilibrium ?
- Answer: In general 'No'. But 'Yes' in case of Potential Games.

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How the people react with belief  $m_t = \bar{m}_t^{(k)}$ :

$$\mathcal{J}(\alpha, (\bar{m}_t^{(k)})_{t \in [0,T]}) = \mathbb{E}\left(\int_0^T \left(L(x_t, \alpha_t) + f(x_t, \bar{m}_t^{(k)})\right) dt + g(x_T, \bar{m}_T^{(k)})\right)$$

$$-\partial_t u^{(k+1)} - \sigma \Delta u^{(k+1)} + H(x, \nabla u^{(k+1)}) = f(x, \bar{m}_t^{(k)})$$
$$\alpha^{(k+1)}(t, x) = -D_p H(x, \nabla u^{(k+1)}(t, x))$$

 The Fokker-Planck equation tells us how the real distribution evolves.

$$\partial_t m^{(k+1)} - \sigma \Delta m^{(k+1)} + \operatorname{div}(\alpha^{(k+1)}(t, x)m^{(k+1)}) = 0, \quad m(0) = m_0$$

And the agents adjust their belief by choosing  $m^{(k+1)}$  the solution of precedent Fokker-Planck.

Fictitious play define by induction the sequence  $\{(u^k, m^k)\}_{k \in \mathbb{N}}$  as follows: Choose  $m^{(0)}$  arbitrary, then for k = 1, 2, ...:

$$\begin{cases} (i) & -\partial_t u^{(k+1)} - \sigma \Delta u^{(k+1)} + H(x, \nabla u^{(k+1)}) = f(x, \bar{m}^{(k)}(t)) \\ (ii) & \partial_t m^{(k+1)} - \sigma \Delta m^{(k+1)} - \operatorname{div}(m^{(k+1)}D_p H(x, \nabla u^{(k+1)})) = 0 \\ (iii) & m^{(k+1)}(0) = m_0, \ u^{(k+1)}(x, T) = g(x, \bar{m}^{(k)}(T)) \end{cases}$$

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- Can we say that we have always convergence ?
- Potential Games
- How can we define the Potential Mean Field Game ?

#### Potential Mean Field Game

• We call a Mean Field Game as a Potential Mean Field Game, if there exist  $F, G : \mathcal{P}(\mathbb{T}^d) \to \mathbb{R}$  such that:

$$\lim_{s \to 0} \frac{F(m + s(m' - m)) - F(m)}{s} = \int_{\mathbb{T}^d} f(x, m) \mathrm{d}(m' - m)(x)$$

$$\lim_{s \to 0} \frac{G(m + s(m' - m)) - G(m)}{s} = \int_{\mathbb{T}^d} g(x, m) \mathrm{d}(m' - m)(x)$$

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$$\lim_{s \to 0} \frac{G(m + s(m' - m)) - G(m)}{s} = \int_{\mathbb{T}^d} g(x, m) d(m' - m)(x)$$

• For example the following quite general case is indeed a Potential MFG:

$$f(x,m) = \int_{\mathbb{T}^d} \phi(x,y) \, \mathrm{d}m(y), \quad g(x,m) = \int_{\mathbb{T}^d} \psi(x,y) \, \mathrm{d}m(y)$$

if  $\phi, \psi$  are symmetric.

#### Theorem (Cardaliaguet P., Hadikhanloo S.)

Suppose the conditions (\*) hold. If the MFG is Potential, then every accumulation point of the precompact sequence  $\{(u^k, m^k)\}_{k \in \mathbb{N}}$  which is constructed by a Fictitious Play, is indeed an equilibrium. Hence, if the equilibrium is unique then the later converge to the unique equilibrium.

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Suppose the conditions (\*) hold. If the MFG is Potential, then every accumulation point of the precompact sequence  $\{(u^k, m^k)\}_{k \in \mathbb{N}}$  which is constructed by a Fictitious Play, is indeed an equilibrium. Hence, if the equilibrium is unique then the later converge to the unique equilibrium.

Because of the existence of regularity conditions in case  $\sigma \neq 0$ , the proof framework is different for Second and First order MFG.

# Second Order MFG ( $\sigma = 1$ )

• Suppose  $\{(u^{(k)}, m^{(k)})\}_{k \in \mathbb{N}}$  is constructed by a Fictitious Play. Define for every  $k \in \mathbb{N}$ :

$$w_t^{(k)}(x) = m_t^{(k)}(x)\alpha^{(k)}(t,x) = -m_t^{(k)}(x)D_pH(x,\nabla u^{(k)}(t,x))$$

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• For any pair  $(m, w) \in \mathcal{C}([0, T] \times \mathbb{T}^d, \mathbb{R}) \times \mathcal{C}([0, T], \mathbb{R}^d)$  which satisfies:

$$\partial_t m - \sigma \Delta m + \operatorname{div}(w) = 0,$$

define the potential:

$$\Phi(m,w) =$$

 $\int_0^T \int_{\mathbb{T}^d} m_t(x) H^*(x, -w_t(x)/m_t(x)) dt dx + \int_0^T F(m_t) dt + G(m_T)$ where  $H^*(x, q) = \sup_p \langle q, p \rangle - H(x, p).$ 

$$\Phi(\bar{m}^{(k+1)}, \bar{w}^{(k+1)}) - \Phi(\bar{m}^{(k)}, \bar{w}^{(k)}) \le -\frac{a_k}{k} + \frac{C}{k^2},$$
  
where  $a_k = \int_0^T \int_{\mathbb{T}^d} \bar{m}^{(k)} \|\bar{w}^{(k)}/\bar{m}^{(k)} - w^{(k)}/m^{(k)}\|^2 \ge 0.$ 

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where  $a_k = \int_0^T \int_{\mathbb{T}^d} \bar{m}^{(k)} \|\bar{w}^{(k)}/\bar{m}^{(k)} - w^{(k)}/m^{(k)}\|^2 \geq 0.$   
Since  $\Phi(\bar{m}^{(k)}, \bar{w}^{(k)}), \ k \in \mathbb{N}$  is bounded below we have:

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$$\sum_{k \in \mathbb{N}} \frac{a_k}{k} < +\infty \quad \Rightarrow \quad \lim_{k \to \infty} \frac{a_1 + a_2 + \dots + a_k}{k} = 0.$$

$$\Phi(\bar{m}^{(k+1)}, \bar{w}^{(k+1)}) - \Phi(\bar{m}^{(k)}, \bar{w}^{(k)}) \leq -\frac{a_k}{k} + \frac{C}{k^2},$$
  
where  $a_k = \int_0^T \int_{\mathbb{T}^d} \bar{m}^{(k)} \|\bar{w}^{(k)}/\bar{m}^{(k)} - w^{(k)}/m^{(k)}\|^2 \geq 0.$   
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• Any accumulation point of the precompact set:

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$$k \in \mathbb{N}, \quad (u^{(k+1)}, m^{(k)}, \bar{m}^{(k)}, \bar{w}^{(k+1)})$$

is of the form  $(u, m, m, -mD_pH(\nabla u))$  where (u, m) is a MFG equilibrium.

# <u>First</u> Order MFG ( $\sigma = 0$ )

• Let 
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- There exist a measurable function  $\Psi:\mathbb{T}^d\to \Gamma$  where

$$\Psi^{k+1}(x) = \operatorname{argmin}_{\gamma \in \Gamma, \gamma(0) = x} \mathcal{J}(\gamma, (e_t \sharp \eta^k)_{t \in [0,T]})$$

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where  $e_t \sharp \eta^k$  is the push-forward measure on  $\mathbb{T}^d$  at time t. • Set the real distribution made by this belief:

$$\theta^{k+1} = \Psi^{k+1} \sharp m_0.$$

$$\Phi(\eta) = \int_{\Gamma} \int_{0}^{T} L(\gamma_{t}, \dot{\gamma}_{t}) \, \mathrm{d}t \, \mathrm{d}\eta(\gamma) + \int_{0}^{T} F(e_{t} \sharp \eta) \, \mathrm{d}t + G(e_{T} \sharp \eta)$$

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• One can show that  $\{\Phi(\eta^k)\}_{k\in\mathbb{N}}$  is (almost) decreasing:

$$\Phi(\eta^{k+1}) - \Phi(\eta^k) \le -\frac{a_k}{k} + \frac{C}{k^2}$$
$$a_k = \int_{\Gamma} \mathcal{J}(\gamma, \eta^k) \, \mathrm{d}(\eta^k - \theta^{k+1})(\gamma)$$
$$= \int_{\Gamma} \mathcal{J}(\gamma, \eta^k) \, \mathrm{d}\eta^k - \inf_{\theta \in \mathcal{P}_0(\Gamma)} \int_{\Gamma} \mathcal{J}(\gamma, \eta^k) \, \mathrm{d}\theta \ge 0.$$

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• There exist C > 0 so that  $|a_k - a_{k+1}| \le \frac{C}{k}$ .

• Then  $a_k \to 0$  which yields our result: for any cluster point  $\bar{\eta} \in \mathcal{P}_0(\Gamma)$ :

$$\int_{\Gamma} \mathcal{J}(\gamma, \bar{\eta}) \, \mathrm{d}\bar{\eta} = \inf_{\theta \in \mathcal{P}(\Gamma), e_0 \sharp \theta = m_0} \int_{\Gamma} \mathcal{J}(\gamma, \bar{\eta}) \, \mathrm{d}\theta$$

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• Then his cost will be:

$$\mathcal{J}(\alpha^{i}, x^{-i}) = \int_{0}^{T} \left( L(\alpha^{i}_{t}, x^{i}_{t}) + f(x^{i}_{t}, m_{t,N}) \right) \mathrm{d}t + g(x^{i}_{T}, m_{T,N}).$$

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• Here the question is: if  $N \to \infty$  does the distribution  $\lim_{N\to\infty} \bar{\eta}_N$  exist and if yes then is it equal to MFG equilibrium ?

#### Theorem (P. Cardaliaguet, S. Hadikhanloo)

Suppose the conditions (\*) hold and there is a unique First Order MFG equilibrium. Consider for every  $N \in \mathbb{N}$  the initial points  $X_N^1, X_N^2, \ldots, X_N^N \in \mathbb{T}^d$  so that:

 $m_{0,N} \to m_0, \quad N \to \infty.$ 

Then for every  $\epsilon > 0$  a Fictitious play of a First Order MFG with N-players can reach to a  $\epsilon$ -neighborhood of equilibrium whenever N is enough large.