

Population balance-based optimal control of a crystallization process

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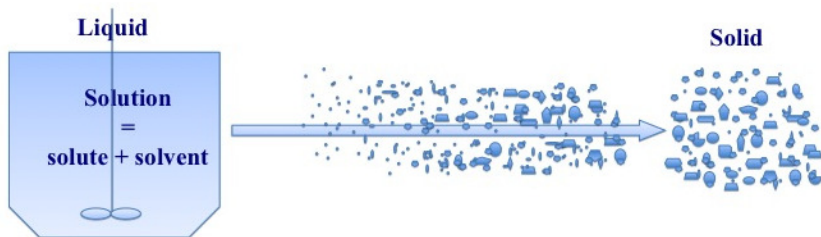
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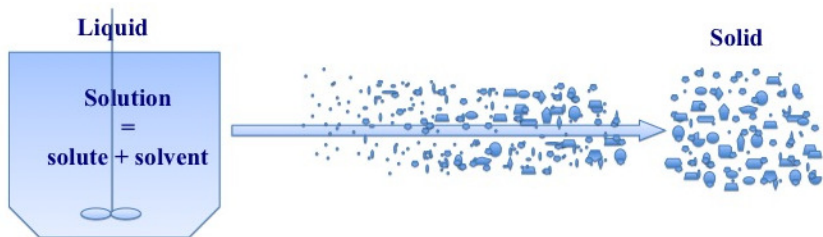


- 1 Context
- 2 Mathematical modelling and process dynamics
- 3 Optimal control of the crystalization of α -lactose monohydrate
 - Problem
 - Reduced model for control
 - Results
- 4 Conclusions

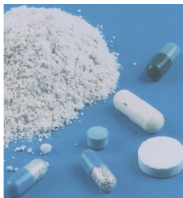
Crystallization process



Crystallization process

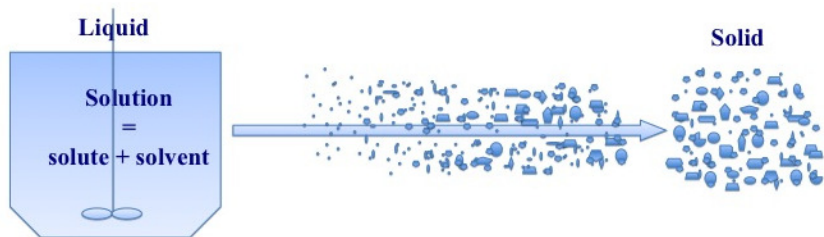


Product meets the set of specifications of the industry

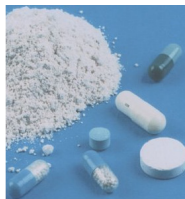


pharmaceutical

Crystallization process



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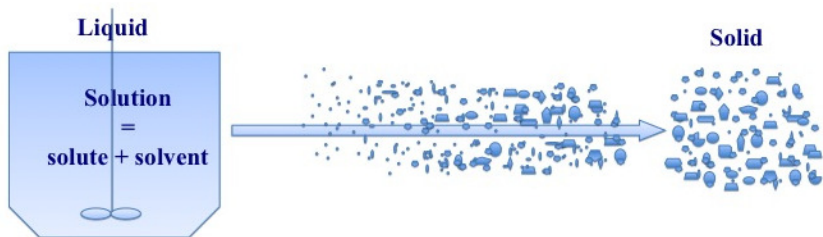


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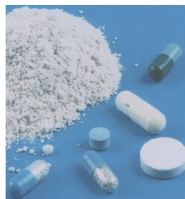


chemical

Crystallization process



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pharmaceutical

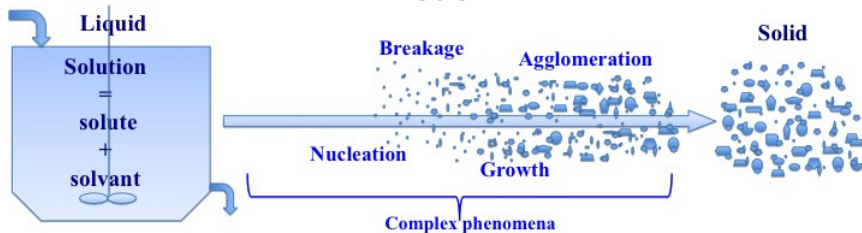


chemical



agri-food

Problem



- Complex phenomena during the crystallization
- Complex operating mode
- Difficulty in controlling the process

Aim of process : To meet product specifications

- Desired particle size distribution
- Fabrication of high quality materials
- Maximum yield

Study

Control of crystallization of α -lactose monohydrate most commonly used form of lactose (milk sugar) in seeded semi-batch mode

⇒ Product meets the set of specifications of the industry **LACTALIS**

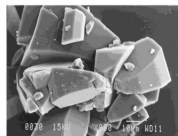
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Proprieties of α -lactose monohydrate

- Used as carrier and stabilizer of aromas and pharmaceutical products due to its bland flavor



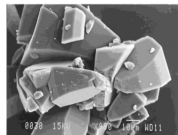
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Control of crystallization of α -lactose monohydrate most commonly used form of lactose (milk sugar) in seeded semi-batch mode

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- Added to tablets and capsules as a filler, due to good physical properties and low price

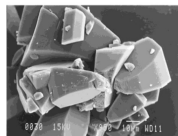
Study

Control of crystallization of α -lactose monohydrate most commonly used form of lactose (milk sugar) in seeded semi-batch mode

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Proprieties of α -lactose monohydrate

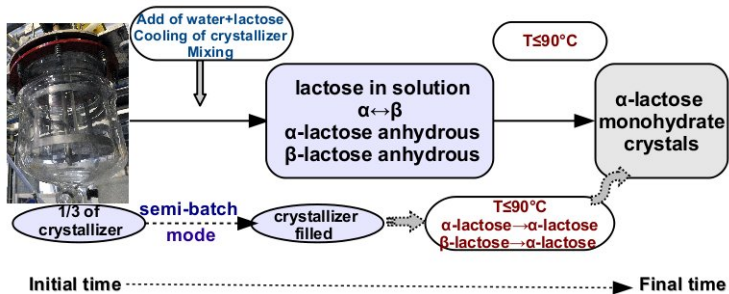
- Used as carrier and stabilizer of aromas and pharmaceutical products due to its bland flavor
- Added to tablets and capsules as a filler, due to good physical properties and low price
- Available as powder in different grades, depending on particle size distribution, density and flowability

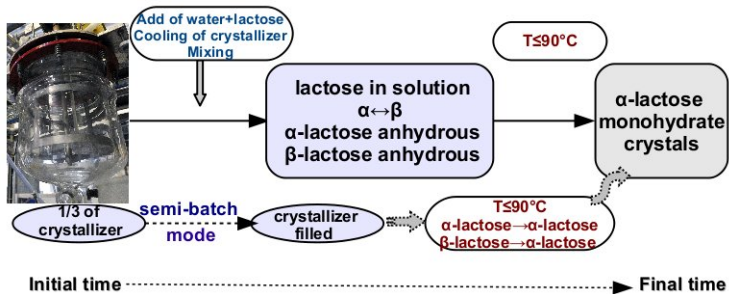


Outline

- 1 Mathematical modelling and process dynamics
- 2 Optimal control of the crystallization of α -lactose monohydrate
- 3 Conclusions

- 1 Context
- 2 Mathematical modelling and process dynamics
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Crystallization of α -lactose monohydrate in semi-batch mode

Crystallization of α -lactose monohydrate in semi-batch mode

Mathematical model

- Mass balances : $m_{\text{H}_2\text{O}}(t)$, $m_\alpha(t)$, $m_\beta(t)$,
- Energy balances : $T(t)$, $T_{\text{jacket}}(t)$,
- Population balance : $n(L, t)$.

Mass balance of solvent (water)

- Water molecule integrated in α -lactose crystal : Loss due to crystallization
- Feed of solution during semi-batch phase.

$$\frac{dm_{\text{H}_2\text{O}}(t)}{dt} = - \underbrace{\left(1 - \frac{1}{R}\right) \frac{dm_{\text{cry}}(t)}{dt}}_{\frac{dm_{\text{H}_2\text{O}} \text{C}_{\text{cry}}}{dt}} + q_{\text{H}_2\text{O}}(t)$$

$$\frac{dm_{\text{cry}}(t)}{dt} = 3k_v \rho_{\text{cry}} G(C_\alpha(t), C_\beta(t), T(t)) V(t) \int_0^\infty n(L, t) L^2 dL$$

$$C_\alpha = \frac{m_\alpha}{m_{\text{H}_2\text{O}}}, \quad C_\beta = \frac{m_\beta}{m_{\text{H}_2\text{O}}}$$

Mass balance of α -lactose in liquid phase

- Loss due to crystallization
- Loss due to mutarotation $\alpha \rightarrow \beta$
- Gain due to mutarotation $\beta \rightarrow \alpha$
- Gain through feed of solution in semi-batch phase

$$\dot{m}_{\alpha}^{+}(t) = q_{\text{H}_2\text{O}}(t)C_{\alpha,0}$$

$$\frac{dm_{\alpha}(t)}{dt} = -\frac{1}{R} \frac{dm_{\text{cry}}(t)}{dt} + [-k_1(T(t))m_{\alpha}(t) + k_2(T(t))m_{\beta}(t)] + q_{\text{H}_2\text{O}}(t)C_{\alpha,0}$$

$$m_{\alpha} = C_{\alpha}m_{\text{H}_2\text{O}}, \quad m_{\beta} = C_{\beta}m_{\text{H}_2\text{O}}$$

Mass balance of β -lactose

- Loss due to mutarotation $\beta \rightarrow \alpha$
- Gain due to mutarotation $\alpha \rightarrow \beta$
- Gain due to feed of solution in semi-batch phase

$$\dot{m}_{\beta}^{+}(t) = q_{\text{H}_2\text{O}}(t)C_{\beta,0}$$

$$\frac{dm_{\beta}(t)}{dt} = k_1(T(t))m_{\alpha}(t) - k_2(T(t))m_{\beta}(t) + q_{\text{H}_2\text{O}}(t)C_{\beta,0}$$

Mass balance of β -lactose

- Loss due to mutarotation $\beta \rightarrow \alpha$
- Gain due to mutarotation $\alpha \rightarrow \beta$
- Gain due to feed of solution in semi-batch phase

$$\dot{m}_{\beta}^{+}(t) = q_{\text{H}_2\text{O}}(t)C_{\beta,0}$$

$$\frac{dm_{\beta}(t)}{dt} = k_1(T(t))m_{\alpha}(t) - k_2(T(t))m_{\beta}(t) + q_{\text{H}_2\text{O}}(t)C_{\beta,0}$$

Total volume of slurry :

$$V(t) = \frac{m_{\alpha}(t)}{\rho_{\text{lac},\alpha}} + \frac{m_{\beta}(t)}{\rho_{\text{lac},\beta}} + \frac{m_{\text{cry}}(t)}{\rho_{\text{cry}}} + \frac{m_{\text{H}_2\text{O}}(t)}{\rho_{\text{H}_2\text{O}}}$$

Mass balance of β -lactose

- Loss due to mutarotation $\beta \rightarrow \alpha$
- Gain due to mutarotation $\alpha \rightarrow \beta$
- Gain due to feed of solution in semi-batch phase

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Total volume of slurry :

$$V(t) = \frac{m_{\alpha}(t)}{\rho_{\text{lac},\alpha}} + \frac{m_{\beta}(t)}{\rho_{\text{lac},\beta}} + \frac{m_{\text{cry}}(t)}{\rho_{\text{cry}}} + \frac{m_{\text{H}_2\text{O}}(t)}{\rho_{\text{H}_2\text{O}}}$$

Crystal mass :

$$m_{\text{cry}}(t) = k_v \rho_{\text{cry}} V(t) \int_0^{\infty} n(L, t) L^3 dL$$

Thermodynamic balance equation

- Heating and cooling : $T_{sp}(t) \rightarrow T_{jacket}(t) \rightarrow T(t)$ (identified from experimental data)
- Heat created by chemical reaction
- Heating or cooling due to temperature difference with feed

$$\frac{dT(t)}{dt} = P_1 \left\{ -P_2(T(t) - T_{ref}) + UA(t)(T_{jacket}(t) - T(t)) + q_{H_2O}(t)(Cp_{H_2O} + Cp_{\alpha}c_{\alpha,0} + Cp_{\beta}c_{\beta,0})(T_{H_2O} - T_{ref}) - \Delta H(T_{ref})\frac{dm_{cry}(t)}{dt} \right\}$$

$$P_1 = \frac{1}{(m_{H_2O}(t)Cp_{H_2O} + m_{\alpha}(t)Cp_{\alpha} + m_{\beta}(t)Cp_{\beta} + m_{cry}(t)Cp_{cry})}$$

$$P_2 = \frac{dm_{H_2O}(t)}{dt}Cp_{H_2O} + \frac{dm_{\alpha}(t)}{dt}Cp_{\alpha} + \frac{dm_{\beta}(t)}{dt}Cp_{\beta} + \frac{dm_{cry}(t)}{dt}Cp_{cry}$$

Population balance equation

$$\underbrace{\frac{\partial (V(t)n(L, t))}{\partial t}}_{\text{accumulation}} + \underbrace{G(C_\alpha(t), C_\beta(t), T(t)) \frac{\partial (V(t)n(L, t))}{\partial L}}_{\text{growth}} = \underbrace{-a(L) V(t)n(L, t) + \int_L^\infty a(L')b(L' \rightarrow L) V(t)n(L', t) dL'}_{\text{breakage}}$$

$$n(L=0, t) = \frac{B(C_\alpha(t), C_\beta(t), T(t))}{G(C_\alpha(t), C_\beta(t), T(t))} \quad \text{Boundary condition}$$

$$n(L, t=0) = n_0(L) \quad \text{Initial condition (seed)}$$

$n(L, t)$ = crystal size distribution

$T(t)$ = crystallizer temperature

a, b = rates of breakage

$c_{\alpha/\beta}$ = concentration of α/β -lactose in solution

$V(t)$ = volume of slurry

G = growth rate

B = birth rate

$n_0(L)$ = seed

Moments

Moment μ_i of the crystal size distribution $n(L, t)$:

$$\mu_i(t) = \int_0^{\infty} n(L, t) L^i dL$$

For $i = 0$, $\mu_0 \sim$ number of crystals

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For $i = 1$, $\mu_1 \sim$ length of crystals

For $i = 2$, $\mu_2 \sim$ surface of crystals

Moments

Moment μ_i of the crystal size distribution $n(L, t)$:

$$\mu_i(t) = \int_0^{\infty} n(L, t) L^i dL$$

For $i = 0$, $\mu_0 \sim$ number of crystals

For $i = 1$, $\mu_1 \sim$ length of crystals

For $i = 2$, $\mu_2 \sim$ surface of crystals

For $i = 3$, $\mu_3 \sim$ volume of crystals

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Mathematical model

- Mass balances : $m_{\text{H}_2\text{O}}(t)$, $m_{\alpha}(t)$, $m_{\beta}(t)$

↔ 3 ODE + integral = Integro-differential equations

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- Energy balances : $T(t)$, $T_{\text{jacket}}(t)$

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Mathematical model

- Mass balances : $m_{\text{H}_2\text{O}}(t)$, $m_{\alpha}(t)$, $m_{\beta}(t)$

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- Energy balances : $T(t)$, $T_{\text{jacket}}(t)$

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- Population balance : $n(L, t)$ of particles of size L

↔ 1 PDE

Mathematical model

- Mass balances : $m_{\text{H}_2\text{O}}(t)$, $m_{\alpha}(t)$, $m_{\beta}(t)$

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↔ 2 ODE + integral = Integro-differential equations

- Population balance : $n(L, t)$ of particles of size L

↔ 1 PDE

Problem

Set of Integro-differential equations coupled + PDE + nonlinearity

Optimal control problem

By acting on the feed rate of solution $q_{\text{H}_2\text{O}}(t)$, on the set-point temperature $T_{\text{sp}}(t)$ and on the crystal seed $n_0(L)$ we wish to

1. Specific criterion

steer the process in such a way that the growth of particles within the size range $130\mu\text{m} \leq L \leq 330\mu\text{m}$ is maximized.

2. Non-specific criterion

minimize the weighted mean size diameter $d_{43} = \frac{\int_0^\infty n(L, t_f) L^4 dL}{\int_0^\infty n(L, t_f) L^3 dL}$

States :

$n(L, t)$, $c_\alpha(t)$, $c_\beta(t)$, $m_{\text{H}_2\text{O}}(t)$, $T(t)$, $T_{\text{jacket}}(t)$

Dependent states : $m_{\text{cry}}(t)$, $V(t)$

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Controls :

$$u_1(t) = T_{\text{sp}}(t) = \text{set-point temperature}$$

$$u_2(t) = q_{\text{H}_2\text{O}}(t) = \text{feed rate of solution}$$

States :

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Parameters :

$n_0(L) = \text{crystals size distribution of seed of given mass}$

States :

$n(L, t)$, $c_\alpha(t)$, $c_\beta(t)$, $m_{\text{H}_2\text{O}}(t)$, $T(t)$, $T_{\text{jacket}}(t)$
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Parameters :

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Cost function :

$k_v \rho_{\text{cry}} V(t_f) \int_{L_1}^{L_2} L^3 n(L, t_f) dL = \text{crystal mass in interval } [L_1, L_2]$

Use moment approach

$$\mu_i(t) = \int_0^{\infty} L^i n(L, t) dL, \quad i = 0, \dots, N$$

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Population balance splits into

$$\frac{d\mu_i(t)}{dt} + \frac{V'(t)}{V(t)}\mu_i(t) - iG(c_\alpha(t), c_\beta(t), T(t))\mu_{i-1}(t) = 0,$$

$$i = 1, \dots, N$$

$$\frac{d\mu_0(t)}{dt} = \frac{V'(t)}{V(t)}\mu_0(t) - B(c_\alpha(t), c_\beta(t), T(t)) = 0$$

Parameters :

$$p_i = \mu_i(0), i = 0, \dots, N \quad \text{moments of unknown seed}$$

New set of states :

$$\mu_0(t), \dots, \mu_N(t), T(t), T_{\text{jacket}}(t), c_\alpha(t), c_\beta(t), m_{\text{H}_2\text{O}}(t)$$

New set of states :

$$\mu_0(t), \dots, \mu_N(t), T(t), T_{\text{jacket}}(t), c_\alpha(t), c_\beta(t), m_{\text{H}_2\text{O}}(t)$$

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Parameters :

Unknown moments of the unknown seed of known mass

New set of states :

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Cost function :

???

Procedure

- Choose target CSD $n_{\text{target}}(L)$, which has its bulk of crystal mass in the range $[L_1, L_2]$.
- Normalize to unit mass and compute moments of target $\mu_{i,\text{target}}$.

Obtain weighted least squares objective

$$\min \rightarrow \sum_{i=0}^N w_i (\mu_i(t_f) - \mu_{i,\text{target}})^2$$

- Pull moments of unknown $n(L, t_f)$ to moments of target such that third moment matches

$$\begin{aligned} &\text{minimize} && \sum_{i=1}^N w_i (\mu_i(t_f) - \mu_{i,\text{target}})^2 \\ &\text{subject to} && \text{population dynamics (moments)} \\ &&& \text{mass balances} \\ &&& \text{energy balance} \\ &&& \text{initial conditions} \\ &&& V_0 \leq V(t) \leq V_{\max} \\ &&& 0 \leq T(t) \leq 70^\circ\text{C} \\ &&& 0 \leq p \leq P_{\max} \\ &&& \text{supersaturation} \end{aligned}$$

Model : PDE+ODEs

Cost function :

$$k_v \rho_{\text{cry}} V(t_f) \int_{L_1}^{L_2} L^3 n(L, t_f) dL$$

Controls : $T_{\text{cnsg}}(t)$, $q_{\text{H}_2\text{O}}(t)$

Parameter : $n(L, t = 0)$

Model : PDE+ODEs

cost function :

$$k_v \rho_{\text{cry}} V(t_f) \int_{L_1}^{L_2} L^3 n(L, t_f) dL$$

Controls : $T_{\text{cnsg}}(t)$, $q_{\text{H}_2\text{O}}(t)$

Parameters : $n(L, 0)$

Reduce model

(Moment approach)



Model : ODEs

Cost function : min \rightarrow

$$\sum_{i=0}^N (\mu_i(t_f) - \mu_{i,\text{target}})^2$$

Controls : $T_{\text{cnsg}}(t)$, $q_{\text{H}_2\text{O}}(t)$

Parameters : $\mu_i(0)$

Model : PDE+ODEs

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Controls : $T_{\text{cnsg}}(t)$, $q_{\text{H}_2\text{O}}(t)$

Parameter : $\mu_i(0)$

Control
 \Rightarrow
PSOPT, ACADO

Optimal control :

$$T_{\text{cnsg}}^*(t), q_{\text{H}_2\text{O}}^*(t)$$

Optimal parameters :

$$\mu_i(0)^*$$

Model : PDE+ODEs

Cost function :

$$k_v \rho_{\text{cry}} V(t_f) \int_{L_1}^{L_2} L^3 n(L, t_f) dL$$

Controls : $T_{\text{cnsg}}(t), q_{\text{H}_2\text{O}}(t)$

Parameters : $n(L, 0)$

Reduce the model
(Moment approach)



Model : ODEs

Cost function : $\min \rightarrow$

$$\sum_{i=0}^N (\mu_i(t_f) - \mu_{i,\text{target}})^2$$

Controls : $T_{\text{cnsg}}(t), q_{\text{H}_2\text{O}}(t)$

Parameters : $\mu_i(0)$

Simulate



Optimal controls :

$$T_{\text{cnsg}}^*(t), q_{\text{H}_2\text{O}}^*(t)$$

Optimal parameters :

$$n(L, 0)^*$$

MAXENT



Reconstruct

Control



PSOPT, ACADO

Optimal controls :

$$T_{\text{cnsg}}^*(t), q_{\text{H}_2\text{O}}^*(t)$$

Optimal parameters :

$$\mu_i(0)^*$$

Numerical resolution

- **ACADO** : software environment and algorithm collection for automatic control and dynamic optimization.

 <http://www.acadotoolkit.org>

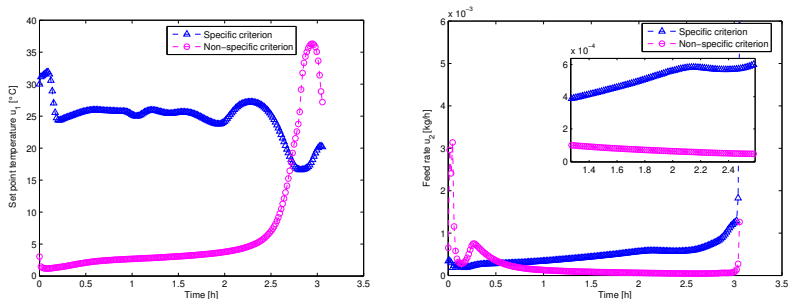
- **PSOPT** :

 <http://www.psopt.org/Home>

Method of reconstruction of distribution : **Maximum entropy**

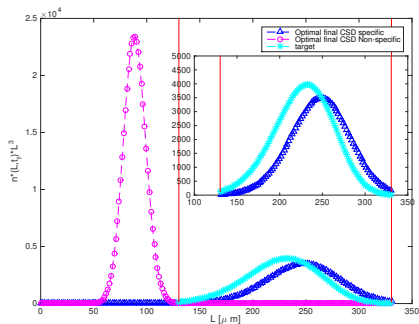
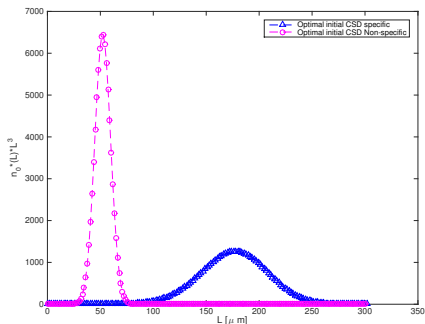
$$(P) \quad \begin{array}{l} \text{maximize} \\ \text{subject to} \end{array} \quad \begin{array}{l} S[p] = - \int_0^{\infty} p(x) \ln p(x) dx \\ \int_0^{\infty} p(x) x^i dx = \mu_i, i = 0, \dots, N \end{array}$$

Results



Optimal regulation of set-point temperature $u_1^*(t) = T_{sp}^*(t)$ (left) and optimal feed rate $u_2^*(t) = q_{H_2O}^*(t)$ (right).

Results



Optimal initial seed $n_0^*(L)$ (left) and optimal final CSD $n^*(L, t_f)$ (right)

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- Use of the moment approach to obtain a reduced model for control
- Optimal control techniques based on mathematical modelling were used to enhance product quality in solvated crystallization

- Use of the moment approach to obtain a reduced model for control
- Optimal control techniques based on mathematical modelling were used to enhance product quality in solvated crystallization
- The crystal mass of α -lactose monohydrate produced in a specific size range may be substantially increased over standard approaches if optimization is used

THANK you for your attention

