

Smoothness of the Metric Projection onto Nonconvex Bodies in Hilbert Spaces

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IMAG - Université de Montpellier

Journées SMAI-MODE, Toulouse, March 23, 2016

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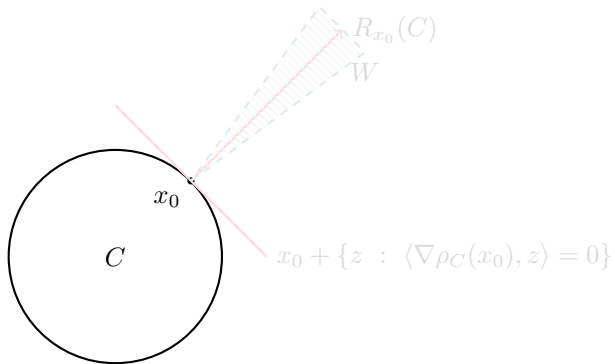
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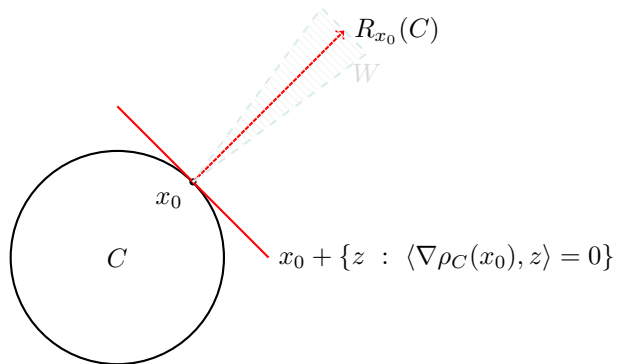
Theorem 1.1 (Holmes, 1973)

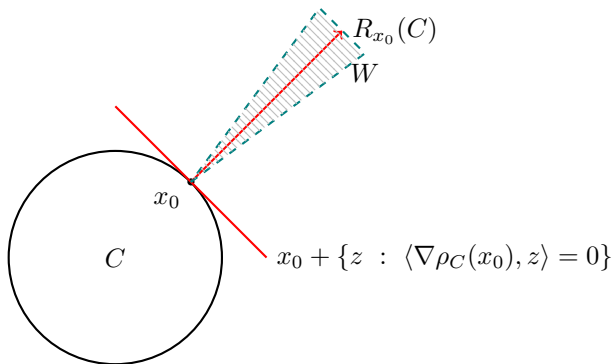
Let C be a convex body of a Hilbert space X such that $0 \in \text{int } C$ and $\text{bd } C$ is a \mathcal{C}^{p+1} -submanifold near $x_0 \in \text{bd } C$. Let ρ_C be the Minkowski functional of C . Then, there exists an open neighborhood W of the open normal ray

$$R_{x_0}(C) = \{x_0 + t\nabla\rho_C(x_0) : t > 0\},$$

such that $P_C(\cdot)$ is of class \mathcal{C}^p on W .







Elements of the Proof:

- (i) The smoothness of $\text{bd } C$ at x_0 is equivalent to the smoothness of $\rho_C(\cdot)$ at x_0 (regardless possible translations).
- (ii) Furthermore, the exterior normal vector of $\text{bd } C$ at x_0 is $\nu = \nabla \rho_C(x_0) / \|\nabla \rho_C(x_0)\|$.
- (ii) The distance function $d_C(\cdot)$ is of class \mathcal{C}^1 on $X \setminus C$.

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- (iv) At each point $u_0 \in R_{x_0}(C)$, we can choose two neighborhoods $U \in \mathcal{N}(u_0)$ and $V \in \mathcal{N}(x_0)$ such that the function

$$F : U \times V \rightarrow X$$

$$(u, v) \mapsto u - v - d_C(u) \frac{\nabla \rho_C(v)}{\|\nabla \rho_C(v)\|}$$

satisfies that $F(u, v) = 0$ if and only if $v = P_C(u)$.

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Definition 2.1

For a closed set S , a point $x_0 \in S$ and a point $u \in X$ we define:

- (a) $\text{Proj}_S(u) = \{s \in S : d_S(u) = \|u - s\|\}$. When $\text{Proj}_S(u)$ is a singleton, we write $P_S(u)$ instead.
- (b) The **Proximal normal cone** of S at x_0 as

$$N^P(S; x_0) = \{\zeta \in X : \exists t > 0, x_0 \in \text{Proj}_S(x_0 + t\zeta)\}.$$

(c) Whenever the Proximal normal cone of S at x_0 has the form

$$N^P(S; x_0) = \{t\nu : t \geq 0\},$$

for some $\nu \in \mathbb{S}_X$, we define the **open normal ray** and the **λ -truncated open normal ray** of S at x_0 as

$$R_{x_0}(S) = \{x_0 + t\nu : t > 0\}$$

$$R_{x_0, \lambda}(S) = \{x_0 + t\nu : t \in (0, \lambda)\}.$$

Definition 2.2 (Prox-Regular sets)

For $r \in (0, +\infty]$ and $\alpha > 0$, we say that S is **(r, α) -prox-regular at x_0** if for every $x \in S \cap B_X(x_0, \alpha)$ and every $\zeta \in N^P(S; x) \cap \mathbb{B}_X$ we have that

$$x \in \text{Proj}_S(x + t\zeta), \quad \text{for every real } t \in [0, r]. \quad (1)$$

We say that S is **r -prox-regular at x_0** if it is (r, α) -prox-regular at x_0 for some $\alpha > 0$.

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Definition 2.3

For $r \in (0, +\infty]$ and $\alpha > 0$ we define the sets

$$\mathcal{R}_S(x_0, r, \alpha) := \left\{ x + tv : \begin{array}{l} x \in S \cap B_X(x_0, \alpha), \\ t \in [0, r), v \in N^P(S; x) \cap \mathbb{B}_X \end{array} \right\},$$

$$\mathcal{W}_S(x_0, r, \alpha) := \left\{ u \in X : \begin{array}{l} \text{Proj}_S(u) \cap B_X(x_0, \alpha) \neq \emptyset, \\ d_S(u) < r \end{array} \right\}.$$

In general, $\mathcal{R}_S(x_0, r, \alpha) \supset \mathcal{W}_S(x_0, r, \alpha)$, but the equality doesn't always hold.

Theorem 2.4 (Mazade, 2011)

The following assertions are equivalent:

- (i) S is (r, α) -prox-regular at x_0 ;
- (ii) $\mathcal{W}_S(x_0, r, \alpha)$ is open and d_S is \mathcal{C}^1 on $\mathcal{W}_S(x_0, r, \alpha) \setminus S$ with

$$\nabla d_S(u) = \frac{u - P_S(u)}{d_S(u)};$$

- (iii) For any $x \in S \cap B(x_0, \alpha)$ and $\zeta \in N^P(S; x)$ one has

$$\langle \zeta, x' - x \rangle \leq \frac{\|\zeta\|}{2r} \|x' - x\|^2 \quad \text{for all } x' \in S.$$

Moreover, if S is (r, α) -prox-regular at x_0 , then $\mathcal{R}_S(x_0, r, \alpha)$ and $\mathcal{W}_S(x_0, r, \alpha)$ coincide.

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Theorem 3.1

Let $O_0 \subseteq X$ be an open set and $f : O_0 \subseteq X \rightarrow \mathbb{R}$ be a function of class \mathcal{C}^{p+1} near $x_0 \in X$ such that $\nabla f(x_0) = 0$. Assume that $\overline{\text{epi } f}$ is r -prox-regular at $(x_0, f(x_0))$. For the constant

$$\lambda = \min \left\{ r, \left(-2 \inf \{ \langle u, D^2 f(x_0) u \rangle : u \in \mathbb{B}_X \} \right)^{-1} \right\}$$

there exists an open neighborhood W of $R_{(x_0, f(x_0)), \lambda}(\text{epi } f)$ such that

- (a) $d_{\text{epi } f}$ is of class \mathcal{C}^{p+1} on W ;
- (b) $P_{\text{epi } f}$ is of class \mathcal{C}^p on W .

Sketch of proof

Denote $S := \overline{\text{epi } f}$ and $v_0 := (x_0, f(x_0))$. We will write $u = (u_1, u_2)$ for every $u \in X \times \mathbb{R}$.

For $\alpha > 0$ small enough and $O := \mathcal{W}_S(v_0, r, \alpha) \subset X \times \mathbb{R}$ we can ensure:

- 1 $\pi_X(O) \subseteq O_0$, f is \mathcal{C}^{p+1} on $\pi_X(O)$.
- 2 $d_S(\cdot)$ is \mathcal{C}^1 on O .
- 3 For $x \in \pi_X(O)$, $N^P(S; (x, f(x))) = \{t(\nabla f(x), -1) : t \geq 0\}$.
- 4 $P_S[(v + N^P(S; v)) \cap O] = v$, for $v \in S \cap O$.
- 5 $R_{v_0, \lambda}(S) \subset O$.

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Fix $u_0 \in R_{v_0, \lambda}(S)$ and choose $U \in \mathcal{N}_X(u_0)$ and $V \in \mathcal{N}(v_0)$ with $U, V \subseteq O$. Define

$$F : U \times V \rightarrow X \times \mathbb{R} \\ (u, v) \mapsto u - v - d_S(u)\varphi(v),$$

where $\varphi(v) = \frac{(\nabla f(v_1), -1)}{\|(\nabla f(v_1), -1)\|}$ for all $v \in V$.

If we choose correctly U and V , we can assure that

$$F(u, v) = 0 \iff v = P_S(u).$$

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If we choose correctly U and V , we can assure that

$$F(u, v) = 0 \iff v = P_S(u).$$

It is not hard to see that

$$D_2F(u_0, v_0) = -(\text{id}_{X \times \mathbb{R}} + d_S(u)D\varphi(v_0)),$$

and, using that $\nabla f(x_0) = 0$, we can show by simple computation that

$$D\varphi(v_0)h = (D^2f(x_0)h_1, 0), \quad \forall h \in X \times \mathbb{R}.$$

Using that $d_S(u_0) < \lambda$, we prove that $D_2F(u_0, v_0)$ is bijective, and so we can apply the **Implicit Function Theorem (IFT)**:

IFT: d_S is of class \mathcal{C}^1 on U , and so F is of class \mathcal{C}^1 on $U \times V$. Then, there exist $U_1 \in \mathcal{N}(u_0)$ and $V_1 \in \mathcal{N}(v_0)$ and a mapping $\phi : U_1 \rightarrow V_1$ such that

- (i) ϕ is of class \mathcal{C}^1 ;
- (ii) For each $u' \in U_1$, $F(u', \phi(u')) = 0$;
- (iii) For each $(u', v') \in U_1 \times V_1$, $F(u', v') = 0 \implies v = \phi(u')$.

We can see that $\phi = P_S$ on U_1 and so P_S is of class \mathcal{C}^1 and d_S is of class \mathcal{C}^2 .

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Theorem 3.2

Let $S \subseteq X$ be a closed body near $x_0 \in \text{bd } S$. Assume that there exist $r \in (0, +\infty]$ and $\alpha > 0$ such that $B_X(x_0, \alpha) \cap \text{bd } S$ is a \mathcal{C}^{p+1} -submanifold and that S is r -prox-regular at x_0 .

Then there exists a neighborhood V of $R_{x_0, r}(S)$ such that

- d_S is of class \mathcal{C}^{p+1} on V ;
- P_S is of class \mathcal{C}^p on V .

Furthermore, if the set S is (α, r) -prox-regular at x_0 , then

- d_S is of class \mathcal{C}^{p+1} on $\mathcal{W}_S(x_0, r, \alpha) \setminus S$;
- P_S is of class \mathcal{C}^p on $\mathcal{W}_S(x_0, r, \alpha) \setminus S$.

Sketch of proof:

We will prove only the second part, which entails the first one.

- We can regard (near x_0) the set S as the epigraph of a \mathcal{C}^{p+1} function $f : O_0 \subseteq Z \rightarrow \mathbb{R}$, where $Z := T_{x_0}(\text{bd } S)$ (which is an hyperplane). In particular, we have that $\nabla f(z_0) = 0$, where $z_0 := \pi_Z(x_0)$.
- Considering $X = Z \times \mathbb{R}$ and noting that $\underline{x_0} = (z_0, f(z_0))$, we can choose O_0 small enough such that $\text{epi } f$ is r -prox-regular at $(z_0, f(z_0))$.

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- We can prove, thanks to the r -prox-regularity, that

$$\inf \{ \langle z, D^2 f(z_0)z \rangle : z \in \mathbb{B}_Z \} \geq -\frac{1}{r},$$

and so, the constant λ in Theorem 3.1 is greater than $r/2$.

- Using Theorem 3.1, d_S is of class \mathcal{C}^{p+1} on $\mathcal{W}_S(x_0, r/2, \alpha) \setminus S$.

Now, take $x \in B_X(x_0, \alpha) \cap \text{bd } S$ and $u \in R_{x,r}(S)$ with $d_S(u) \geq \frac{r}{2}$. We can choose $\alpha' > 0$ small enough such that $B_X(x, \alpha')$ is included in $B_X(x_0, \alpha)$ and S is (r, α') -prox-regular at x .

We get that $d_S(\cdot)$ is of class \mathcal{C}^{p+1} in $\mathcal{W}_S(S, r/2, \alpha') \setminus S$ and so:

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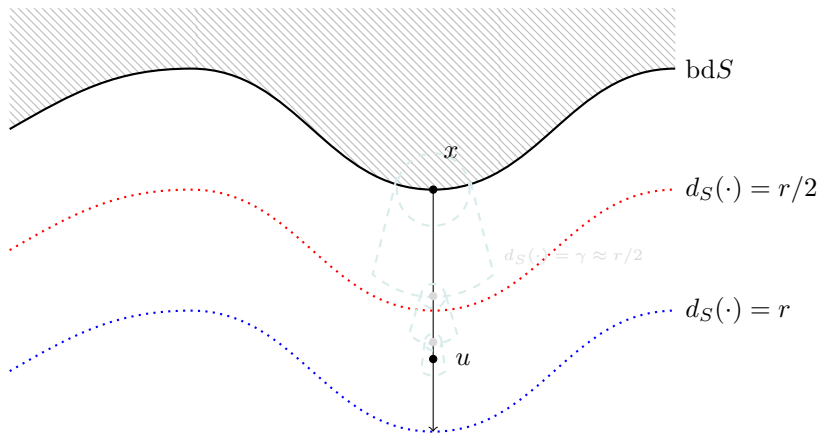
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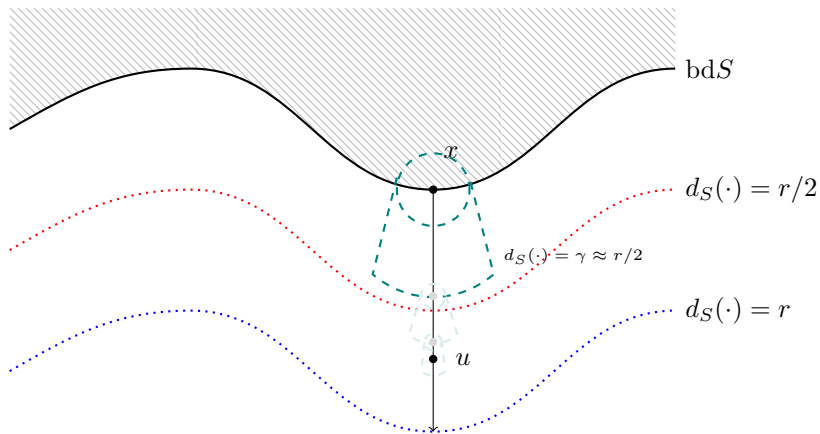
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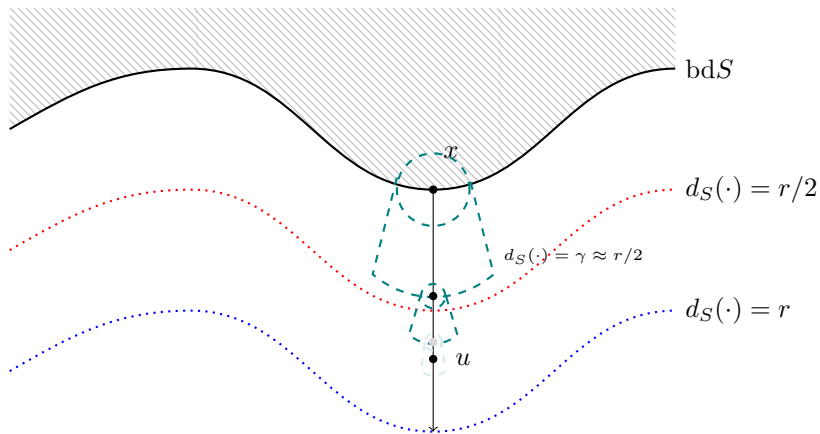
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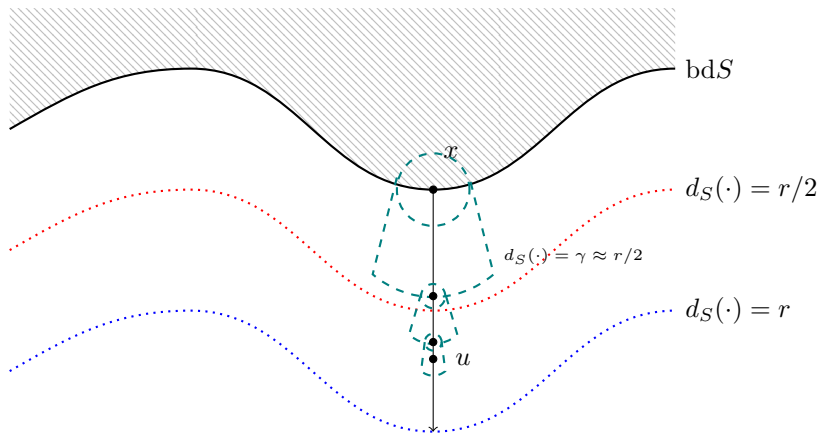
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Since u is arbitrary, we conclude that $d_S(\cdot)$ is of class \mathcal{C}^{p+1} at each element of the set

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The proof is complete, recalling that $\mathcal{R}_S(x_0, r, \alpha) = \mathcal{W}_S(x_0, r, \alpha)$. □

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Some comments:





- We proved the same result of Theorem 3.2 when S is itself a \mathcal{C}^{p+1} -submanifold, instead of a nonconvex body. We were based on the work of Poly and Raby [6].
- With L. Thibault, we proved the converse of Theorem 3.2, adding an extra hypothesis. We followed the ideas of Fitzpatrick and Phelps [2]. This is an ongoing work.
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Thank you for your attention.